

Minimal Projections in Tensor-Product Spaces

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1. INTRODUCTION

A *projection* of a Banach space X onto a subspace V is a bounded linear map $P: X \twoheadrightarrow V$ such that $P^2 = P$. (The arrow with two heads denotes a surjective map.) For many applications, a projection with nearly minimal norm is sought. The greatest lower bound for $\|P\|$ is the *relative projection constant* of V in X :

$$\lambda(V, X) = \inf\{\|P\|: P \in \mathcal{L}(X, V), P(X) = V, P^2 = P\}.$$

The *absolute projection constant* of a Banach space Y is defined by

$$\lambda(Y) = \sup\{\lambda(Y, Z): Z \supset Y\}.$$

These numbers may be infinite.

Our interest here is in the projection constants of subspaces of tensor-product spaces. For example, if $G \subset X$ and $H \subset Y$ (all Banach spaces), how is $\lambda(G \otimes H, X \otimes Y)$ related to $\lambda(G, X)$ and $\lambda(H, Y)$? This problem does not become properly posed until the topology of $X \otimes Y$ has been specified. It is convenient to assume that a *reasonable* norm α has been defined on the

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algebraic tensor product $X \otimes Y$. This term means that in addition to the usual axioms of a norm, we require

$$\varepsilon(t) \leq \alpha(t) \leq \gamma(t), \quad t \in X \otimes Y \tag{1}$$

$$\alpha|(A \otimes B)t| \leq \|A\| \|B\| \alpha(t), \quad A \in \mathcal{L}(X, X_1), B \in \mathcal{L}(Y, Y_1). \tag{2}$$

In Eq. (1), ε denotes the injective tensor-product norm, also termed the “least cross-norm whose associate is also a cross norm” [13]. (In Schatten’s monograph ε is denoted by λ , but here we wish to use λ for projection constants.) The norm γ is the projective tensor-product norm, or the “greatest cross-norm.”

In the nomenclature of Diestel and Uhl [7], α is a reasonable cross-norm with the additional property (2). Our terminology agrees with that of Gilbert and Leih [8] except that we do not insist that α be defined for all pairs of Banach spaces X, Y .

The completion of $X \otimes Y$ with the norm α is denoted by $X \otimes_\alpha Y$. If $G \subset X$ and $H \subset Y$, we use the notation $G \overline{\otimes}_\alpha H$ to denote the closure of $G \otimes H$ in $X \otimes_\alpha Y$. This may differ from $G \otimes_\alpha H$ in cases where α is of “general character” and therefore has a meaning for any pair of normed spaces. See [7, p. 231] and [13, p. 39].

Our main result is an extension of a recent theorem of Jameson and Pinkus [10]. They proved that if S and T are compact Hausdorff spaces, each containing infinitely many points, then the relative projection constant of $C(S) + C(T)$ as a subspace of $C(S \times T)$ is 3. Our result (Theorem 8) states that under the same hypotheses, and with G and H finite-dimensional subspaces containing the constant functions, the subspace

$$G \otimes_\varepsilon C(T) + C(S) \otimes_\varepsilon H$$

has relative projection constant at least 3. Our lower bound is sharp when $\lambda(G, C(S)) = \lambda(H, C(T)) = 1$, as occurs in the situation considered by Jameson and Pinkus.

Another of our results, Theorem 1, gives upper and lower bounds on the relative projection constant of $G \overline{\otimes}_\alpha H$ as a subspace of $X \otimes_\alpha Y$. This theorem is accompanied by various examples which indicate that the upper and lower bounds can be attained.

2.

THEOREM 1. *Consider four Banach spaces, $G \subset X, H \subset Y$. Let α be a reasonable norm on $X \otimes Y$. The following inequality is valid for relative projection constants:*

$$\max\{\lambda(G, X), \lambda(H, Y)\} \leq \lambda(G \overline{\otimes}_\alpha H, X \otimes_\alpha Y) \leq \lambda(G, X) \cdot \lambda(H, Y).$$

Proof. In order to prove the inequality on the right, let P and Q be projections of X onto G and Y onto H , respectively. Then $P \otimes_\alpha Q$ projects $X \otimes_\alpha Y$ onto $G \bar{\otimes}_\alpha H$ and has norm $\|P\| \cdot \|Q\|$. Hence

$$\lambda(G \bar{\otimes}_\alpha H, X \otimes_\alpha Y) \leq \|P\| \cdot \|Q\|.$$

By taking an infimum on P and Q we obtain the desired inequality.

In order to prove the inequality on the left, let P be a projection of $X \otimes_\alpha Y$ onto $G \bar{\otimes}_\alpha H$. Since the case $H = 0$ is trivial, we assume $H \neq 0$ and select $h \in H$ with $\|h\| = 1$. Select $\varphi \in Y^*$ such that $\|\varphi\| = 1$ and $\varphi(h) = 1$. Define $\tilde{\varphi}: X \otimes_\alpha Y \rightarrow X$ by putting at first

$$\tilde{\varphi}(x \otimes y) = \varphi(y) \cdot x \quad (x \in X, y \in Y)$$

and then extending $\tilde{\varphi}$ by linearity and continuity. The continuous extension is possible because

$$\begin{aligned} \left\| \tilde{\varphi} \left(\sum x_i \otimes y_i \right) \right\| &= \left\| \sum \varphi(y_i) \cdot x_i \right\| = \left\| \left(\sum x_i \otimes y_i \right) (\varphi) \right\| \\ &\leq \varepsilon \left(\sum x_i \otimes y_i \right) \|\varphi\| \leq \alpha \left(\sum x_i \otimes y_i \right). \end{aligned}$$

In this inequality, ε denotes the smallest reasonable norm (λ in Schatten's notation). Hence $\varepsilon \leq \alpha$. Also $\sum x_i \otimes y_i$ is interpreted as a linear operator from Y^* to X whose value at ψ is $\sum \psi(y_i) \cdot x_i$. The inequality then shows that $\|\tilde{\varphi}\|_\alpha \leq 1$, where $\|\tilde{\varphi}\|_\alpha$ is defined as the supremum of $\|\tilde{\varphi}(v)\|/\alpha(v)$, $v \in X \otimes_\alpha Y$.

Now define $Q: X \rightarrow G$ by putting $Qx = \tilde{\varphi}[P(x \otimes h)]$. It is easily seen that Q maps X into G , that $Qg = g$ for all $g \in G$, that Q is bounded, and that $\|Q\| \leq \|P\|_\alpha$. Hence $\|P\|_\alpha \geq \lambda(G, X)$. By taking an infimum on P we obtain $\lambda(G \bar{\otimes}_\alpha H, X \otimes_\alpha Y) \geq \lambda(G, X)$. By symmetry we obtain $\lambda(G \bar{\otimes}_\alpha H, X \otimes_\alpha Y) \geq \lambda(H, Y)$. This establishes the desired inequality. ■

COROLLARY 1. *Let G, X, Y be Banach spaces, with $G \subset X$. Let α be a reasonable norm on $X \otimes Y$. Then the relative projection constants obey*

$$\lambda(G, X) = \lambda(G \bar{\otimes}_\alpha Y, X \otimes_\alpha Y).$$

COROLLARY 2. *If, in Theorem 1, $\lambda(H, Y) = 1$ then (with α as above)*

$$\lambda(G \bar{\otimes}_\alpha H, X \otimes_\alpha Y) = \lambda(G, X).$$

Now let S and T be compact Hausdorff spaces. If $G \subset X = C(S)$, $Y = C(T)$, and if ε is the smallest reasonable norm, then by a theorem of

Grothendieck [14] $X \otimes_{\varepsilon} Y = C(S \times T)$ and $G \otimes_{\varepsilon} C(T) = C(T, G)$. Also, it is clear that

$$\lambda(C(T), C(S \times T)) = 1.$$

Hence, from the first Corollary,

$$\lambda(G \otimes_{\varepsilon} C(T), C(S \times T)) = \lambda(G, C(S)).$$

Recall also that if $G \subset C(S)$ and $\dim G < \infty$, then

$$\lambda(G, C(S)) = \lambda(G).$$

The upper bound and the lower bound given in Theorem 1 can be attained in nontrivial examples, as will be indicated in some of the following results.

An operator L is said to satisfy Daugavet's equation if $\|I - L\| = 1 + \|L\|$. This is a property of compact operators in $C[0, 1]$ and $L_1[0, 1]$. See [5] and [1].

LEMMA 1. *Let K be a closed set which is not open in a compact Hausdorff space S . Let $R: C(S) \rightarrow C(K)$ be the restriction map, and let E be any bounded linear extension map from $C(K)$ to $C(S)$. Then the projection ER obeys "Daugavet's equation": $\|I - ER\| = 1 + \|ER\| = 1 + \|E\|$.*

Proof. It is clear that $\|I - ER\| \leq 1 + \|ER\|$. In order to prove that $\|I - ER\| \geq 1 + \|ER\|$ we distinguish two cases. First, suppose that $\|E\| > 1$. Let $1 < \rho < \|E\|$. Then there exists $y \in C(K)$ such that $\|y\| = 1$ and $\|Ey\| > \rho$. Select $\sigma \in S$ such that $|(Ey)(\sigma)| = \|Ey\|$. We can assume that $(Ey)(\sigma) = \|Ey\|$. By the Tietze Extension Theorem, there exists $x \in C(S)$ such that $Rx = y$, $x(\sigma) = -1$, and $\|x\| = 1$. Note that $\sigma \notin K$ since $(Ey)(\sigma) > 1$ while $(Ey)(s) \leq 1$ for $s \in K$. Now we have

$$\|ER - I\| \geq (ERx - x)(\sigma) = \|Ey\| + 1 > \rho + 1.$$

Since ρ was arbitrary between 1 and $\|E\|$, $\|ER - I\| \geq \|E\| + 1$. Observe that in this part of the proof we did not use the hypothesis that K is not open.

In the second case, assume that $\|E\| = 1$. There is a net $s_{\alpha} \in S \setminus K$ such that $\lim s_{\alpha} \in K$. By the Tietze Theorem, there exist functions $x_{\alpha} \in C(S)$ such that $Rx_{\alpha} = 1$, $x_{\alpha}(s_{\alpha}) = -1$, and $\|x_{\alpha}\| = 1$. Then, by continuity of $E1$,

$$\|ER - I\| \geq (ERx_{\alpha} - x_{\alpha})(s_{\alpha}) = (E1)(s_{\alpha}) + 1 \rightarrow 2. \quad \blacksquare$$

If K is a closed subset of a compact Hausdorff space S , the extension constant of K in S is the number

$$\eta(K, S) = \inf\{\|E\|: E \text{ is a bounded linear extension map from } C(K) \text{ to } C(S)\}.$$

THEOREM 2. *Let K and S be as above, and let J be the ideal in $C(S)$ of functions vanishing on K . Then*

$$\lambda(J, C(S)) = \begin{cases} 1 + \eta(K, S) & \text{if } K \text{ is not open} \\ 1 & \text{if } K \text{ is open.} \end{cases}$$

Moreover, there is a minimal projection on J if and only if there is a minimal extension map from $C(K)$ to $C(S)$.

Proof. If $P: C(S) \rightarrow J$ is a projection, then by Theorem 1 of [6], $P = I - ER$ for some bounded linear extension map. Here R is the restriction map from $C(S)$ to $C(K)$. Now use the preceding Lemma. If K is not open then $\|P\| = 1 + \|E\| \geq 1 + \eta(K, S)$, whence $\lambda(J, C(S)) \geq 1 + \eta(K, S)$. On the other hand, if an extension E is given then $I - ER$ is a projection on J . Hence $\|E\| = \|I - ER\| - 1 \geq \lambda(J, C(S)) - 1$, whence $\eta(K, S) \geq \lambda(J, C(S)) - 1$.

If K is open, a minimal extension is defined by $(Ex)(s) = x(s)$ for $s \in K$ and $(Ex)(s) = 0$ for $s \in S \setminus K$. A minimal projection is defined by $P = I - ER$. Both P and E are of norm 1.

The proof is completed by noting that in these arguments P is minimal if and only if E is minimal. ■

COROLLARY 3. *If K is a closed set in a metric space S , and if J is the ideal in $C(S)$ of functions vanishing on K , then $\lambda(J, C(S)) = 1$ or 2 depending on whether K is open or not. In both cases a minimal projection exists.*

Proof. By the Borsuk–Dugundji Theorem [14, p. 365], there exists a linear extension map of norm 1. The result now follows from Theorem 2. ■

COROLLARY 4. *The set of all projection constants $\lambda(J, C(S))$ for S a compact Hausdorff space and J an ideal in $C(S)$ is $\{1\} \cup [2, \infty]$.*

Proof. By Corollary 3, we get values $\lambda = 1$ or 2. By a theorem of Benyamini [2] all numbers in $[1, \infty]$ occur as values of $\eta(K, S)$. By Corollary 1, all numbers in $[2, \infty]$ occur as values of $\lambda(J, C(S))$. It is noteworthy that in Benyamini’s theorem K can be fixed and taken to be the unit cell in a nonseparable Hilbert space, with its weak topology. ■

Remark. In Benyamini’s example, the extension constants are exact. The same is true for the examples of Corson and Lindenstrauss [4]. In all of these cases, the corresponding ideals possess minimal projections.

THEOREM 3. *Let S and T be metric spaces. Let F_1 and F_2 be closed sets in S and T , respectively, of which at least one has a nonempty boundary. Let*

G and H be the ideals corresponding to F_1 and F_2 . Then $\max\{\lambda(G, C(S)), \lambda(H, C(T))\} = \lambda\{G \otimes_\epsilon H, C(S \times T)\}$.

Proof. By the preceding results, $\max\{\lambda(G, C(S)), \lambda(H, C(T))\} = 2$. Now $G \otimes H$ is an ideal in $C(S \times T)$. Indeed, if $x \in C(S)$, $y \in C(T)$, $g \in G$, and $h \in H$ then

$$(x \otimes y) \cdot (g \otimes h) = (x \cdot g) \otimes (y \cdot h).$$

Since G and H are ideals, $x \cdot g \in G$ and $y \cdot h \in H$. By linearity and continuity we conclude that $zu \in G \otimes H$ if $z \in C(S \times T)$ and $u \in G \otimes H$. By Corollary 3, $\lambda(G \otimes_\epsilon H, C(S \times T)) = 2$. ■

Remark. $G \otimes H$ consists of all functions which vanish on

$$(F_1 \times T) \cup (S \times F_2).$$

THEOREM 4. *If G and H are finite-dimensional subspaces of $C(S)$ and $C(T)$, respectively, then*

$$\lambda(G \otimes_\epsilon H, C(S) \otimes_\epsilon C(T)) = \lambda(G, C(S)) \cdot \lambda(H, C(T)).$$

Proof. The steps in the proof are:

$$\lambda(G \otimes_\epsilon H, C(S) \otimes_\epsilon C(T)) = \lambda(G \otimes_\epsilon H, C(S \times T)) \tag{1}$$

$$= \lambda(G \otimes_\epsilon H) \tag{2}$$

$$= \lambda(G) \lambda(H) \tag{3}$$

$$= \lambda(G, C(S)) \cdot \lambda(H, C(T)). \tag{4}$$

Step 1 uses the fact that $C(S) \otimes_\epsilon C(T)$ is isometric to $C(S \times T)$ if $x \otimes y$ is identified with the function $x(s)y(t)$. Steps 2 and 4 use a remark made above. Step 3 utilizes a theorem from [15], which asserts that for any two finite-dimensional Banach spaces, $\lambda(E \otimes_\epsilon F) = \lambda(E) \lambda(F)$. The proof of this theorem utilizes results in [9]. ■

THEOREM 5. *Let S be a compact metric space and G an ideal in $C(S)$ such that $\lambda[G, C(S)] = 2$. Let H be any hyperplane in (c_0) . Then*

$$\lambda[G \otimes_\epsilon H, C(S) \otimes_\epsilon (c)] < \lambda[G, C(S)] \lambda[H, (c)]. \tag{1}$$

If $\lambda[H, (c_0)] = 1$ then

$$\lambda[G \otimes_\epsilon H, C(S) \otimes_\epsilon (c)] = \max\{\lambda[G, C(S)], \lambda[H, (c)]\}. \tag{2}$$

Proof. The space (c) , of all convergent sequences, is $C(T)$ when T is the set $\{0, 1/n\}_{n=1}^\infty$. By considering the composition of two projections we have (and here we write \otimes in place of \otimes_ε)

$$\lambda[G \otimes H, C(S \times T)] \leq \lambda[G \otimes H, G \otimes (c_0)] \lambda[G \otimes (c_0), C(S \times T)]. \quad (3)$$

If G is the ideal of all functions in $C(S)$ which vanish on a certain closed set $K \subset S$, then $G \otimes (c_0)$ is the ideal of all functions in $C(S \times T)$ which vanish on $F \equiv (K \times T) \cup (S \times \{0\})$. Since $\lambda[G, C(S)] = 2$, K is not open, by Corollary 3, and hence F is not open. By Corollary 3 again,

$$\lambda[G \otimes (c_0), C(S \times T)] = 2. \quad (4)$$

By a theorem in [3], the relative projection constants of hyperplanes in (c_0) lie in the interval $[1, 2)$. Hence

$$\lambda[H, (c_0)] < 2. \quad (5)$$

By the lemma which follows,

$$\lambda[H, (c)] \geq 2. \quad (6)$$

By Corollary 1

$$\lambda[G \otimes H, G \otimes (c_0)] = \lambda[H, (c_0)]. \quad (7)$$

Now by combining (3), (4), (7), and (5) we see that

$$\lambda[G \otimes H, C(S \times T)] < 4. \quad (8)$$

By combining the hypothesis $\lambda[G, C(S)] = 2$ with Eq. (6) we see that

$$\lambda[G, C(S)] \lambda[H, (c)] \geq 4. \quad (9)$$

Thus (1) is established. In order to prove (2), we assume

$$\lambda[H, (c_0)] = 1. \quad (10)$$

Since $\lambda[G, C(S)] = 2 \leq \lambda[H, (c)]$, Theorem 1 implies that

$$\lambda[G \otimes H, C(S \times T)] \geq \max\{\lambda[G, C(S)], \lambda[H, (c)]\} = \lambda[H, (c)] \geq 2. \quad (11)$$

On the other hand, Eqs. (3), (7), (10), and (4) yield

$$\lambda[G \otimes H, C(S \times T)] \leq 2. \quad \blacksquare$$

LEMMA 2. *If H is a hyperplane in (c_0) , then $\lambda[H, (c)] \geq 2$.*

Proof. Every projection $P: (c) \rightarrow H$ is of the form

$$Px = x - \langle \phi, x \rangle z - \langle \psi, x \rangle w$$

with $\langle \phi, x \rangle = \lim x_n$, $\psi \in (l_1)$, $\langle \phi, z \rangle = \langle \psi, w \rangle = 1$, $\langle \phi, w \rangle = \langle \psi, z \rangle = 0$, $H = \ker(\psi)$, $\|\psi\| = 1$.

Given $\varepsilon > 0$, select an integer k such that $|w_k| < \varepsilon$ and $z_k > 1 - \varepsilon$. Select $x \in (c)$ such that $\|x\| = 1$, $\lim x_n = -1$, and $x_k = 1$. Then

$$\begin{aligned} |(Px)_k| &= |x_k + z_k - \langle \psi, x \rangle w_k| \\ &\geq 1 + 1 - \varepsilon - \varepsilon = 2 - 2\varepsilon. \end{aligned}$$

Hence $\|P\| \geq \|Px\| \geq 2 - 2\varepsilon$. ■

3.

In this section we study the projection constants of more complicated subspaces in tensor-product spaces. If $G \subset X$ and $H \subset Y$ are Banach spaces, and if α is a reasonable norm, we can define a subspace W of $X \otimes_\alpha Y$ by

$$W = \alpha\text{-closure in } X \otimes_\alpha Y \text{ of } (G \otimes Y) + (X \otimes H).$$

What can be learned about the relative projection constant of W as a subspace of $X \otimes_\alpha Y$?

THEOREM 6. *Let α be a reasonable norm on $X \otimes Y$. If both G and H are complemented subspaces, then so is W , and*

$$\lambda(W, X \otimes_\alpha Y) \leq \lambda(G, X) + \lambda(H, Y) + \lambda(G, X) \lambda(H, Y).$$

Proof. Let $P: X \rightarrow G$ and $Q: Y \rightarrow H$ be projections. Define a mapping L by

$$L = (P \otimes I_Y) \oplus (I_X \otimes Q).$$

Here we use the Boolean sum operation defined by $A \oplus B = A + B - AB$. This is a bounded linear operator on $X \otimes_\alpha Y$. It is routine to verify that L is a projection onto W , and that $\|L\| \leq \|P\| + \|Q\| + \|P\| \|Q\|$. ■

THEOREM 7. *Let $A: X \rightarrow X$ and $B: Y \rightarrow Y$ be linear operators satisfying Daugavet's equation. Let α be a reasonable norm on $X \otimes Y$. Then the operator*

$$L = (A \otimes_\alpha I) \oplus (I \otimes_\alpha B)$$

on $X \otimes_\alpha Y$ also satisfies Daugavet's equation, and

$$\|L\| = \|A\| + \|B\| + \|A\| \|B\|.$$

Proof. By verifying that the two operators have the same effect on all dyads, $x \otimes y$, we obtain

$$I - L = (I - A) \otimes_\alpha (I - B).$$

From this and elementary results from [13, p. 30] we have

$$\begin{aligned} 1 + \|L\| &\geq \|I - L\| = \|I - A\| \|I - B\| \\ &= (1 + \|A\|)(1 + \|B\|) \\ &= 1 + \|A\| + \|B\| + \|A\| \|B\|. \end{aligned}$$

This proves "half" of our equation. The reverse inequality follows at once from the definition of L and the triangle inequality. ■

THEOREM 8. *Let S and T be compact Hausdorff spaces, each containing infinitely many points. Let G and H be finite-dimensional subspaces containing the constants in $C(S)$ and $C(T)$, respectively. Then each projection of $C(S \times T)$ onto $G \otimes C(T) + C(S) \otimes H$ has norm at least 3.*

Proof. Let $n = \dim(G)$. Select s_1, \dots, s_n in S and $g_1, \dots, g_n \in G$ so that $g_i(s_j) = \delta_{ij}$. Then the operator L defined by $Lx = \sum_{i=1}^n x(s_i) g_i$ is a projection of $C(S)$ onto G .

In the same way, let $m = \dim(H)$, and let M be a projection of $C(T)$ onto H of the form $My = \sum_{i=1}^m y(t_i) h_i$.

The operator $K = (I \otimes M) \oplus (L \otimes I)$ is a projection of $C(S \times T)$ onto the subspace $W = G \otimes C(T) + C(S) \otimes H$. Hence for any $w \in W$ we have $w = Kw$, or

$$\begin{aligned} w(s, t) &= \sum_{\mu=1}^n w(s_\mu, t) g_\mu(s) + \sum_{\nu=1}^m w(s, t_\nu) h_\nu(t) \\ &\quad - \sum_{\mu=1}^n \sum_{\nu=1}^m w(s_\mu, t_\nu) g_\mu(s) h_\nu(t). \end{aligned} \tag{1}$$

Note that since $1 \in G$ and $1 \in H$, we have $L1 = 1$, $M1 = 1$, and

$$\sum_{\mu=1}^n g_\mu = 1, \quad \sum_{\nu=1}^m h_\nu = 1. \tag{2}$$

Now let P be any projection of $C(S \times T)$ onto W . Let $\epsilon > 0$. We will prove that $\|P\| > 3 - \epsilon$.

Since S is compact and infinite, there exists an ω -accumulation point $\sigma \in S$. (See Kelley [11, p. 138].) Likewise, T contains an ω -accumulation point τ . Let c be any number greater than

$$2^n \max_{1 \leq i \leq n} \sum_{u=1}^n |g_u(\sigma) - g_u(s_i)| + 2^m \max_{1 \leq j \leq m} \sum_{r=1}^m |h_r(\tau) - h_r(t_j)|.$$

Let k be an integer so large that

$$k^{-2} [2k + 2kc \|P\| + (m + n)c + c^2 \|P\|] < \varepsilon/2. \tag{3}$$

For $i = 1, \dots, k$ define a neighborhood of σ by

$$\mathcal{N}_i = \left\{ s \in S : \sum_{u=1}^n |g_u(\sigma) - g_u(s)| < c2^{-i} \right\}.$$

Note that for $i = 1, \dots, n$ we have $s_i \in \mathcal{N}_i$. Select inductively points s_{n+1}, \dots, s_k so that

$$s_1, \dots, s_n, s_{n+1}, \dots, s_k \text{ are distinct} \tag{4}$$

$$s_i \in \mathcal{N}_i \quad \text{for } i = 1, \dots, k. \tag{5}$$

In the same way select points t_{m+1}, \dots, t_k so that

$$t_1, \dots, t_m, t_{m+1}, \dots, t_k \text{ are distinct} \tag{6}$$

$$\sum_{r=1}^m |h_r(\tau) - h_r(t_j)| < c2^{-j} \quad \text{for } j = 1, \dots, k. \tag{7}$$

By an argument using partitions of unity, there exist $x_i \in C(S)$ such that $x_i \geq 0$, $x_i(s_j) = \delta_{ij}$, and $\sum_{i=1}^k x_i = 1$ for $1 \leq i, j \leq k$. Similarly, we have $y_j \in C(T)$ with $y_j \geq 0$, $y_j(t_i) = \delta_{ij}$, and $\sum_{j=1}^k y_j = 1$. Define $z_{ij} = x_i \otimes y_j$ ($1 \leq i, j \leq k$). Elementary calculations show that

$$\|z_{ij}\| = 1 \tag{8}$$

$$z_{ij}(s_\mu, t_\nu) = \delta_{i\mu} \delta_{j\nu} \quad (1 \leq i, j, \nu, \mu \leq k) \tag{9}$$

$$\sum_{i=1}^k z_{ij} = 1 \otimes y_j \in W \quad (1 \leq j \leq k) \tag{10}$$

$$\sum_{j=1}^k z_{ij} = x_i \otimes 1 \in W \quad (1 \leq i \leq k). \tag{11}$$

Define $w_{ij} = Pz_{ij}$. From Eqs. (10) and (11) we have

$$\|w_{ij}\| \leq \|P\| \tag{12}$$

$$\sum_{i=1}^k w_{ij} = 1 \otimes y_j \quad (1 \leq j \leq k) \tag{13}$$

$$\sum_{j=1}^k w_{ij} = x_i \otimes 1 \quad (1 \leq i \leq k). \tag{14}$$

Define

$$\varepsilon_{i\mu} = g_\mu(s_i) - g_\mu(\sigma) \quad (1 \leq \mu \leq n, 1 \leq i \leq k) \tag{15}$$

$$\varepsilon'_{jv} = h_v(t_j) - h_v(\tau) \quad (1 \leq v \leq m, 1 \leq j \leq k). \tag{16}$$

From Eqs. (5) and (7) we have

$$\sum_{\mu=1}^n |\varepsilon_{i\mu}| \leq c2^{-i} \quad \text{and} \quad \sum_{v=1}^m |\varepsilon'_{jv}| \leq c2^{-j}. \tag{17}$$

From Eq. (1) we have

$$\begin{aligned} \sum_{ij} w_{ij}(s_i, t_j) &= \sum_{ij\mu} g_\mu(s_i) w_{ij}(s_\mu, t_j) + \sum_{ijv} h_v(t_j) w_{ij}(s_i, t_v) \\ &\quad - \sum_{ij\mu v} g_\mu(s_i) h_v(t_j) w_{ij}(s_\mu, t_v). \end{aligned} \tag{18}$$

The terms on the right side of Eq. (18) are now to be estimated from above. We have, using Eqs. (15), (13), (12), (2), and (17),

$$\begin{aligned} \sum_{ij\mu} g_\mu(s_i) w_{ij}(s_\mu, t_j) &= \sum_{ij\mu} [g_\mu(\sigma) + \varepsilon_{i\mu}] w_{ij}(s_\mu, t_j) \\ &\leq \sum_{j\mu} g_\mu(\sigma)(1 \otimes y_j)(s_\mu, t_j) + \sum_{ij\mu} |\varepsilon_{i\mu}| \|P\| \\ &= \sum_{j\mu} g_\mu(\sigma) + k \|P\| \sum_{i\mu} |\varepsilon_{i\mu}| \\ &= \sum_j 1 + k \|P\| \sum_i c2^{-i} \\ &= k + kc \|P\|. \end{aligned}$$

Similarly, the second term is bounded from above by $k + kc \|P\|$. The third term in Eq. (7) is estimated as follows:

$$\begin{aligned}
 & - \sum_{ijuv} w_{ij}(s_u, t_v) g_u(s_i) h_r(t_j) \\
 &= - \sum_{ijuv} [g_u(\sigma) + \varepsilon_{iu}] |h_r(\tau) + \varepsilon'_{jr}| w_{ij}(s_u, t_r) \\
 &= - \sum_{ijuv} [g_u(\sigma) h_r(\tau)(1 \otimes y_j)(s_u, t_r) + \varepsilon_{iu} h_r(\tau) w_{ij}(s_u, t_r) \\
 &\quad + \varepsilon_{jr} g_u(\sigma) w_{ij}(s_u, t_r) + \varepsilon_{iu} \varepsilon'_{jr} w_{ij}(s_u, t_r)] \\
 &= -1 - \sum_u \varepsilon_{uu} - \sum_r \varepsilon'_{rr} - \sum_{ijuv} \varepsilon_{iu} \varepsilon'_{jr} w_{ij}(s_u, t_r) \\
 &\leq \sum_u |\varepsilon_{uu}| + \sum_r |\varepsilon'_{rr}| + \|P\| \sum_{ijuv} |\varepsilon_{iu} \varepsilon'_{jr}| \\
 &\leq nc + mc + c^2 \|P\|.
 \end{aligned}$$

When these estimates are combined, we have

$$\sum_{ij} w_{ij}(s_i, t_j) \leq 2k + 2kc \|P\| + (m + n)c + c^2 \|P\| \equiv A.$$

It follows, with the help of Eq. (3), that

$$\min_{ij} w_{ij}(s_i, t_j) \leq k^{-2} A < \varepsilon/2.$$

The proof is completed by the following calculation:

$$\begin{aligned}
 0 &\leq 2(1 - x_i)(1 - y_j) \leq 2 \\
 -1 &\leq 1 - 2x_i - 2y_j + 2x_i y_j \leq 1 \\
 \|1 - 2x_i - 2y_j + 2x_i y_j\| &\leq 1 \\
 \|P(1 - 2x_i - 2y_j + 2x_i y_j)\| &\leq \|P\| \\
 \|1 - 2x_i - 2y_j + 2w_{ij}\| &\leq \|P\| \\
 |1 - 2x_i(s_i) - 2y_j(t_j) + 2w_{ij}(s_i, t_j)| &\leq \|P\| \\
 |-3 + 2w_{ij}(s_i, t_j)| &\leq \|P\| \\
 3 - 2w_{ij}(s_i, t_j) &\leq \|P\| \\
 3 - \varepsilon &\leq \|P\|. \blacksquare
 \end{aligned}$$

COROLLARY 5. *If, in Theorem 8, G and H possess norm-1 projections, then $\lambda|W, C(S \times T)| = 3$. Moreover, if P and Q are two norm-1 projections, then*

$$(P \otimes I) \oplus (I \otimes Q)$$

is a minimal projection onto W.

Proof. By Theorem 8,

$$\lambda[W, C(S \times T)] \geq 3.$$

It is easy to verify that the Boolean sum projection has norm at most 3. ■

EXAMPLE. The case $W = C(S) + C(T)$ in Corollary 5 was first given by Jameson and Pinkus [10]. Their methods have been used in the proof of Theorem 8.

EXAMPLE. If $S = T = [0, 1]$, and if G and H are spaces of piecewise linear functions with prescribed knots, then $\lambda(W, C(S \times T)) = 3$.

Remark. In Theorem 8, if we drop the hypothesis that the subspaces G and H contain constants but assume instead the existence of $g \in G$ and $h \in H$ such that

$$\|g\| = \|h\| = 1, \quad \alpha = \inf g(s) > 0, \quad \beta = \inf h(t) > 0,$$

then each projection on W has norm at least $3\alpha\beta$. The proof is almost the same. The functions z_{ij} in the proof would be defined as $gx_i \otimes hy_j$, and at the end of the proof we would have the inequality

$$3g(s_i)h(t_j) - 2w_{ij}(s_i, t_j) \leq \|P\|.$$

THEOREM 9. *Let G be a subspace of $C(S)$ with relative projection constant λ_1 . Let H be a subspace of finite codimension in $C(T)$ with relative projection constant λ_2 . Assume that T has no isolated points. Let $W = C(S) \otimes H + G \otimes C(T)$. Then the relative projection constant of W as a subspace of $C(S \times T)$ does not exceed $\lambda_1(\lambda_2 - 1) + \lambda_2$.*

Proof. Let P and Q be projections of $C(S)$ and $C(T)$ onto G and H , respectively. Define $V = \ker(Q)$, $Q_2 = I - Q$, and $L = (P \otimes Q_2) + (I \otimes Q)$.

It is easily proved that $W = [G \otimes V] \oplus [C(S) \otimes H]$.

Now we prove that L maps $C(S \times T)$ into W . For any $z \in C(S \times T)$, $(P \otimes Q_2)z \in G \otimes V$ and $(I \otimes Q)z \in C(S) \otimes H$. Hence $Lz \in W$.

Next we prove that $Lw = w$ for any $w \in W$. If $g \in G$ and $v \in V$ then $L(g \otimes v) = (Pg \otimes Q_2v) + (Ig \otimes Qv) = (g \otimes v) + (g \otimes 0) = g \otimes v$. By linearity and continuity, $Lz = z$ for all $z \in G \otimes V$. If $x \in C(S)$ and $h \in H$, then $L(x \otimes h) = (Px \otimes Q_2h) + (Ix \otimes Qh) = (Px \otimes 0) + (x \otimes h) = x \otimes h$. By linearity and continuity, $Lz = z$ for all $z \in G \otimes V$. Hence $Lw = w$ for all $w \in W$.

Since Q_2 is compact, Daugavet's Theorem implies that $\|I - Q_2\| = 1 + \|Q_2\|$. Thus $\|Q\| = 1 + \|Q_2\|$.

From the definition of L we have at once $\|L\| \leq \|P\| \|Q_2\| + \|Q\| =$

$\|P\|(\|Q\| - 1) + \|Q\|$. This number is then an upper bound for the projection constant of W . By taking an infimum on P and Q we arrive at the upper bound $\lambda_1(\lambda_2 - 1) + \lambda_2$. ■

Open Problems

1. If G and H are finite-dimensional subspaces in $C(S)$ and $C(T)$, respectively, is the following equation necessarily true?

$$\lambda(G \otimes C(T) + C(S) \otimes H, C(S \times T)) = \lambda(G) + \lambda(H) + \lambda(G)\lambda(H).$$

2. If G and H are as in Question 1, does there necessarily exist a minimal projection of $C(S \times T)$ onto the subspace $W = G \otimes C(T) + C(S) \otimes H$? (By Corollary 5, the answer is affirmative when $\lambda(G) = \lambda(H) = 1$.)

3. Let G, H, W be as in Question 2. Assume that both S and T are infinite sets and that $\max\{\lambda(G), \lambda(H)\} > 1$. Does it necessarily follow that $\lambda(W, C(S \times T)) > 3$?

4. In Theorem 8, can we drop the hypothesis that G and H contain the constant functions?

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